

BLA13-06H-A01 Technical Specification

Item		Specification				Remark		
1	Communication Interface	PWM				Signal Voltage:V	HIGH : min. 2.0V max. Vcc	
							LOW : min. 0.0V max. 0.45V	
						Frame Rate:T	3.0~30ms (Default 14.25ms)	
						CW/Center/CCW:Td	920/1520/2120μs (Resolution recommends less than 1μs.)	
		S.BUS / S.BUS2				Futaba Serial Protocol (Please ask us for more information.)		
2	Rated Voltage	DC 6.0~DC 7.4V				-		
3	Operating Voltage	DC 4.0~DC 8.4V				-		
4	Standby Current	≤ 45mA				at 6.0~7.4V		
5	Starting Current*	1.5A				at 7.4V		
6	Consumption Current*	LL	Me	UL	unit	at 7.4V , No-Load		
		80	160	240	mA	LL : Low Limit Me : Medium Value UL : Upper Limit		
7	Max. Torque*	LL	Me	UL	unit	at 7.4V		
		5.8	8.3	10.8	kgf-cm			
		0.6	0.8	1.1	N-m			
		80.5	115.3	150.0	ozf-in			
8	Rated Torque*	1.7				kgf-cm	at 7.4V 20% of Max. Torque	
		0.16				N-m		
		23.1				ozf-in		
9	No Load Speed*	LL	Me	UL	unit	at 7.4V		
		0.10	0.13	0.16	s/60°			
		375.0	461.5	600.0	°/s			
		62.5	76.9	100.0	rpm			
10	Default Travel Angle	CW 60° (920us) CCW 60° (2120us)				-		
11	Max Travel Angle	CW 90° (920us) CCW 90° (2120us)				Programing tool (CIU-2 or CIU-3,S-Link) required.		
12	BackLash*	≤ 0.5°				-		
13	Operating Temperature Range	-30~+70°C (-22~158°F)				-		
14	Storage Temperature Range	-40~+80°C (-40~176°F)				-		
15	Outer Dimension	28.6 x 13.0 x 32.6mm (1.13 x 0.51 x 1.28 inch)				-		
16	Weight	35g (1.23oz)				with Horn and set screw		
17	Case Material	Upper : AL / Middle : AL / Bottom : AL				-		
18	Gear Set Material	1st,2nd,3rd,4th(Final) : Metal				-		
19	Position Sensor	Magnetic Encoder(Contactless)				-		
20	Motor Type	Brushless DC Motor				-		
21	Cable	Non-Shielded Cable				Cable Length : 150mm (5.90 inch)		
22	Connector	Manufacture	J.A.M. Co., Ltd.					
		Type	FC25-03HG**					
		Mating	FC25-03M** etc.					
		Pin Assignment	1	White	PWM/S.BUS			
		2	Red	Vcc				
		3	Black	GND				
23	MTTF	1000h (Load : 0.67kgf-cm)				Test Condition • Test Voltage : 7.4V • Operating Condition : 0.5Hz sweep (±60°) • Input Pluse : PWM • Calculated by Weibull analysis		
24	Vibration Resistance *	Operating time 1000h (at 7.4V)				Test Condition		
						Frequency range	10 to 500Hz	
		Operating time 300h (at 7.4V)				Sweep Rate	1 oct / min	
						Acceleration	10G (98m/s ²)	
						Vibration axis	X, Y, Z	
						Frequency range	80 to 400Hz	
				Sweep Rate	1.2 min / single-sweep			
				Acceleration	30G (294m/s ²)			
				Vibration axis	X, Y, Z			

* At 23±5°C (Initial Performance Data)

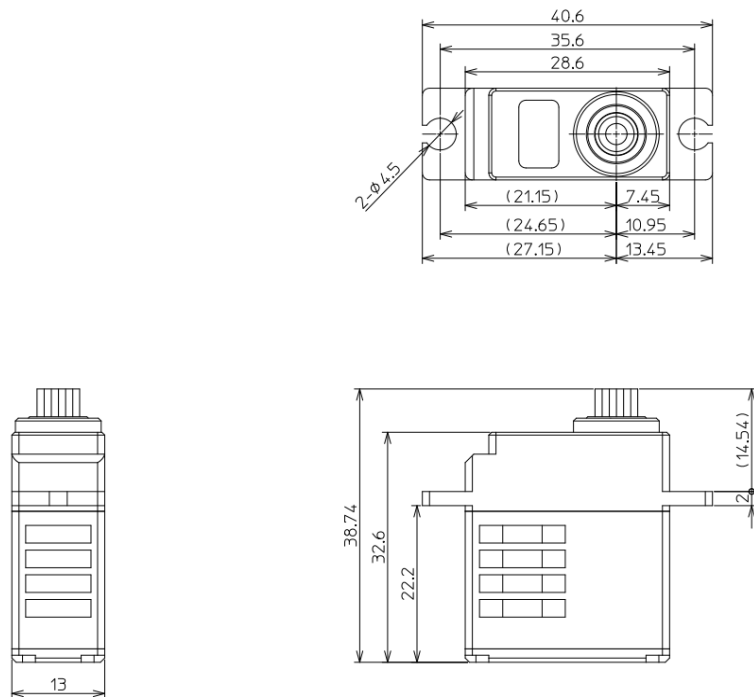
** Custom connector. If necessary, Please use the extension cord sold from Futaba.

All Specifications are subject to change without prior notice.

Caution

- This product SHOULD NOT been used for the devices that is directly related to human life.
- Keep the servo away from an object which produces a strong magnetic field.
There is a possibility of malfunction if the servo is affected by a strong magnetic field.

Outer Dimension



(Unit mm)

Performance Curves

